



GPU Teaching Kit

Accelerated Computing



Module 5.2 – Thread Execution Efficiency

Performance Impact of Control Divergence

Objective

- To learn to analyze the performance impact of control divergence
 - Boundary condition checking
 - Control divergence is data-dependent

Performance Impact of Control Divergence

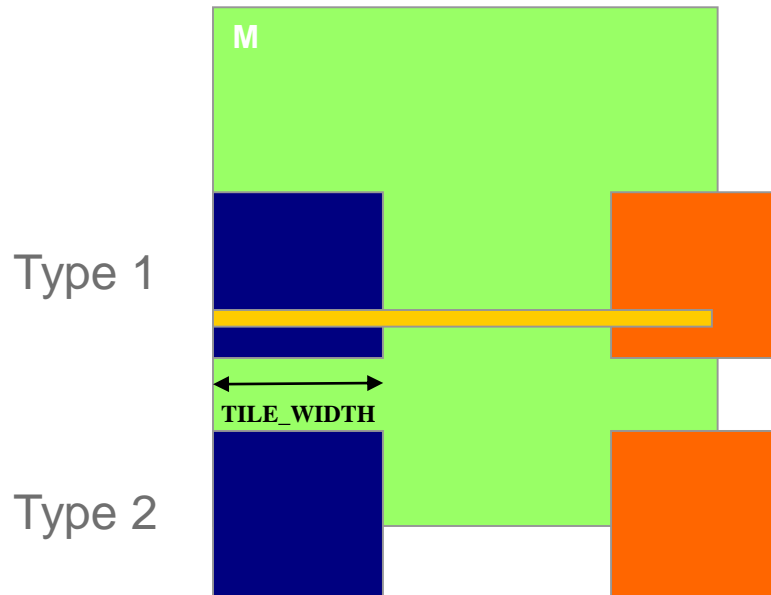
- Boundary condition checks are vital for complete functionality and robustness of parallel code
 - The tiled matrix multiplication kernel has many boundary condition checks
 - The concern is that these checks may cause significant performance degradation
 - For example, see the tile loading code below:

```
if(Row < Width && t * TILE_WIDTH+tx < Width) {  
    ds_M[ty][tx] = M[Row * Width + p * TILE_WIDTH + tx];  
} else {  
    ds_M[ty][tx] = 0.0;  
}
```

```
if (p*TILE_WIDTH+ty < Width && Col < Width) {  
    ds_N[ty][tx] = N[(p*TILE_WIDTH + ty) * Width + Col];  
} else {  
    ds_N[ty][tx] = 0.0;  
}
```

Two types of blocks in loading M Tiles

- 1. Blocks whose tiles are all within valid range until the last phase.
- 2. Blocks whose tiles are partially outside the valid range all the way

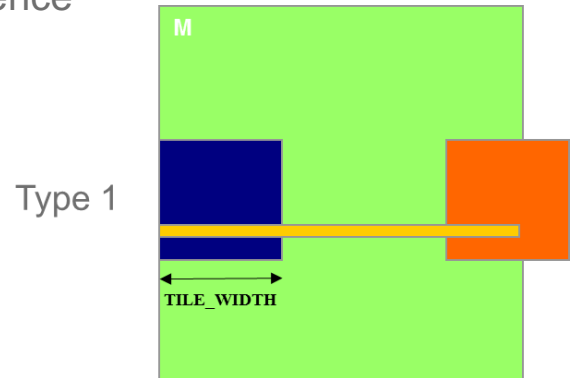


Analysis of Control Divergence Impact

- Assume 16x16 tiles and thread blocks
- Each thread block has 8 warps ($256/32$)
- Assume square matrices of 100x100
- Each thread will go through 7 phases (ceiling of $100/16$)
- There are 49 thread blocks (7 in each dimension)

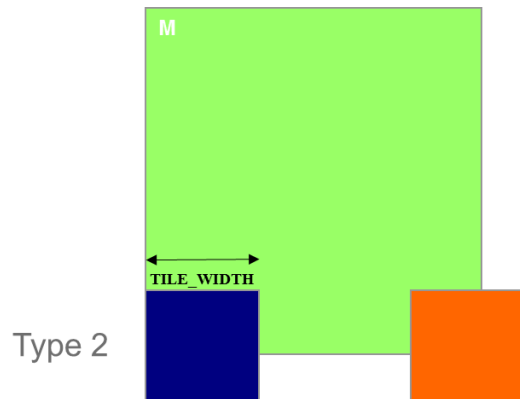
Control Divergence in Loading M Tiles

- Assume 16x16 tiles and thread blocks
- Each thread block has 8 warps ($256/32$)
- Assume square matrices of 100x100
- Each warp will go through 7 phases (ceiling of $100/16$)
- There are 42 ($6*7$) Type 1 blocks, with a total of 336 ($8*42$) warps
- They all have 7 phases, so there are 2,352 ($336*7$) warp-phases
- The warps have control divergence only in their last phase
- 336 warp-phases have control divergence



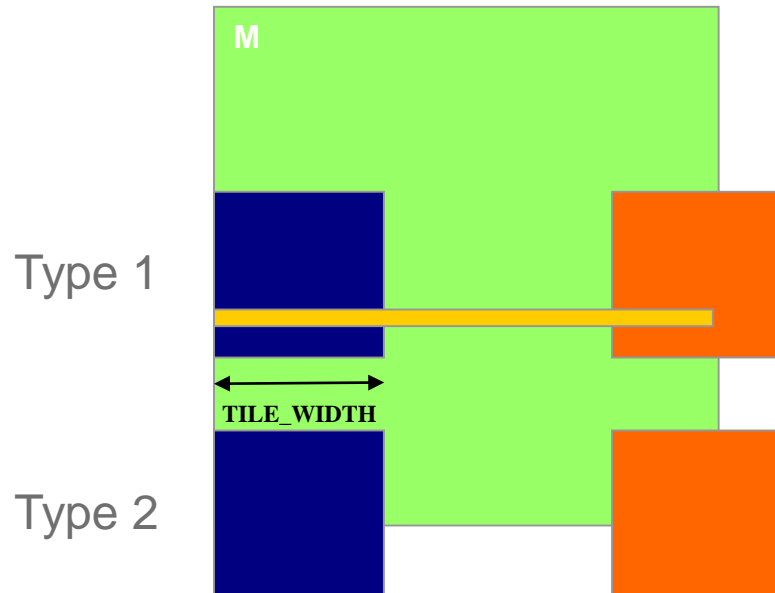
Control Divergence in Loading M Tiles (Type 2)

- Type 2: the 7 block assigned to load the bottom tiles, with a total of 56 (8×7) warps
- They all have 7 phases, so there are 392 (56×7) warp-phases
- The first 2 warps in each Type 2 block will stay within the valid range until the last phase
- The 6 remaining warps stay outside the valid range
- So, only 14 (2×7) warp-phases have control divergence



Overall Impact of Control Divergence

- Type 1 Blocks: 336 out of 2,352 warp-phases have control divergence
- Type 2 Blocks: 14 out of 392 warp-phases have control divergence
- The performance impact is expected to be less than 12% ($350/2,944$ or $(336+14)/(2352+14)$)



Additional Comments

- The calculation of impact of control divergence in loading N tiles is somewhat different and is left as an exercise
- The estimated performance impact is data dependent.
 - For larger matrices, the impact will be significantly smaller
- In general, the impact of control divergence for boundary condition checking for large input data sets should be insignificant
 - One should not hesitate to use boundary checks to ensure full functionality
- The fact that a kernel is full of control flow constructs does not mean that there will be heavy occurrence of control divergence
- We will cover some algorithm patterns that naturally incur control divergence (such as parallel reduction) in the Parallel Algorithm Patterns modules



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